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**To whom it may concern**

**Routines of a quasi-steady  
 ship 'model' powering trial**

**Filter raw data**

```

Filter(t, x, ord_max) :=
    n ← last(t)
    for i ∈ 0..n
        for j ∈ 0..3
            Ai,j ← (ti)j
        X ← geninv(A) · x
        x_0.trend ← A · X
        x_0.red ← x - x_0.trend
        Δt ← tn - t0
        Δx_0.red ← x_0.redn - x_0.red0
        for i ∈ 0..n
            x_0.redi ← x_0.redi - i ·  $\frac{\Delta x_{0.red}}{n}$ 
        x_0.red.F ← cfft(x_0.red)
        for k ∈ ord_max + 1..n - ord_max
            x_0.red.Fk ← 0
        ω ←  $\frac{2 \cdot \pi}{\Delta t}$ 
        for k ∈ 1..ord_max
            |
    
```

$$\begin{aligned}
 & \left[ \begin{array}{l}
 x_{1,\text{red}} F_k \leftarrow x_{0,\text{red}} F_k \cdot (-k \cdot \omega \cdot i) \\
 x_{1,\text{red}} F_{n+1-k} \leftarrow x_{0,\text{red}} F_{n+1-k} \cdot (k \cdot \omega \cdot i) \\
 x_{2,\text{red}} F_k \leftarrow x_{0,\text{red}} F_k \cdot (-k \cdot \omega \cdot i)^2 \\
 x_{2,\text{red}} F_{n+1-k} \leftarrow x_{0,\text{red}} F_{n+1-k} \cdot (k \cdot \omega \cdot i)^2
 \end{array} \right. \\
 & x_{0,\text{red}} \leftarrow \text{Re} \left( \text{icfft} \left( x_{0,\text{red}} F \right) \right) \\
 & x_{1,\text{red}} \leftarrow \text{Re} \left( \text{icfft} \left( x_{1,\text{red}} F \right) \right) \\
 & x_{2,\text{red}} \leftarrow \text{Re} \left( \text{icfft} \left( x_{2,\text{red}} F \right) \right) \\
 & \text{for } i \in 0..n \\
 & \quad x_{0,i} \leftarrow x_{0,\text{red},i} + i \cdot \frac{\Delta x_{0,\text{red}}}{n} + x_{0,\text{trend},i} \\
 & \quad x_{1,\text{trend}} \leftarrow \sum_{k=1}^3 k \cdot X_k \cdot A^{<k-1>} \\
 & \quad x_1 \leftarrow x_{1,\text{red}} + \frac{\Delta x_{0,\text{red}}}{\Delta t} + x_{1,\text{trend}} \\
 & \quad x_{2,\text{trend}} \leftarrow \sum_{k=2}^3 k! \cdot X_k \cdot A^{<k-2>} \\
 & \quad x_2 \leftarrow x_{2,\text{red}} + x_{2,\text{trend}} \\
 & \left[ x_0 \quad x_1 \quad x_2 \right]
 \end{aligned}$$

### Various functions

$$J(D, V, N) := \frac{V}{D \cdot N} \quad KP(\rho, D, P, N) := \frac{P}{\rho \cdot D^5 \cdot N^3}$$

$$Fn(V, L) := \frac{V}{\sqrt{g \cdot L}} \quad CP(\rho, D, P, V) := \frac{P}{\rho \cdot D^2 \cdot V^3}$$

$$VT(\omega_T, v, t) := v_0 + v_1 \cdot \cos(\omega_T \cdot t) + v_2 \cdot \sin(\omega_T \cdot t)$$

$$\text{dir}(\psi_{HG}) := \text{if}\left(\psi_{HG} > \frac{\pi}{2}, 1, -1\right)$$

### Check distributions

```
norm_distr(sampl) :=
  r ← rows(sampl)
  c ← cols(sampl)
  for i ∈ 0.. r - 1
    fract ←  $\frac{2 \cdot (i + 1)}{r + 1} - 1$ 
    dst ← fract
    distr_i ←  $\sqrt{2} \cdot \text{root}(\text{erf}(dst) - \text{fract}, dst)$ 
    for j ∈ 0.. 1
      A_distr_i,j ←  $(\text{distr}_i)^j$ 
    for j ∈ 0.. c - 1
      sampl_sort<j> ← sort(sampl<j>)
      distr_par ← geninv(A_distr) · sampl_sort
      sampl_fair ← A_distr · distr_par
      for j ∈ 0.. c - 1
        distr_par2,j ←  $\frac{\text{distr\_par}_{1,j}}{\sqrt{r}}$ 
      [distr sampl_sort sampl_fair distr_par]
```

**Analyse power supplied at (quasi-)stationary conditions**

```

Supplied( $\omega, \rho, D, \Delta t, V_{HG}, \psi_{HG}, N_S, P_S$ ) :=
for i ∈ 0.. last( $\Delta t$ )
    |
    |  $A_{sup_{i,0}} \leftarrow (N_{S_i})^3$ 
    |  $A_{sup_{i,1}} \leftarrow (N_{S_i})^2 \cdot V_{HG_i}$ 
    |  $A_{sup_{i,2}} \leftarrow (N_{S_i})^2 \cdot \text{dir}(\psi_{HG_i})$ 
    |  $A_{sup_{i,3}} \leftarrow A_{sup_{i,2}} \cdot \cos(\omega \cdot \Delta t_i)$ 
    |  $A_{sup_{i,4}} \leftarrow A_{sup_{i,2}} \cdot \sin(\omega \cdot \Delta t_i)$ 
    |
    |  $X_{sup} \leftarrow \text{geninv}(A_{sup}) \cdot P_S$ 
    |  $P_{S.sup} \leftarrow A_{sup} \cdot X_{sup}$ 
    |  $\Delta P_{S.sup} \leftarrow P_S - P_{S.sup}$ 
    |
    | for k ∈ 0.. 1
    |     |
    |     |  $p_k \leftarrow X_{sup_k}$ 
    |     |  $p_{n_k} \leftarrow \frac{10^6 \cdot p_k}{\rho \cdot D^{(5-k)}}$ 
    |     |
    |     |  $p_2 \leftarrow \text{Stdev}(\Delta P_{S.sup})$ 
    |     |  $c \leftarrow \text{svds}(A_{sup})$ 
    |     |
    |     |  $p_3 \leftarrow \frac{c_4}{c_0}$ 
    |     |
    |     | for k ∈ 0.. 2
    |     |     |
    |     |     |  $v_k \leftarrow \frac{X_{sup_{2+k}}}{X_{sup_1}}$ 
    |     |     |
    |     |     | for i ∈ 0.. last( $\Delta t$ )
    |     |     |     |
    |     |     |     |  $V_{WG_i} \leftarrow VT(\omega, v, \Delta t_i)$ 
    |     |     |     |  $V_{HW_i} \leftarrow V_{HG_i} - V_{WG_i} \cdot \text{dir}(\psi_{HG_i})$ 
    |     |     |     |
    
```

$$\left[ \begin{array}{l} J_{HW_i} \leftarrow J(D, v_{HW_i}, N_{S_i}) \\ K_{P_{sup}_i} \leftarrow KP(\rho, D, P_{S_{sup}_i}, N_{S_i}) \\ \left[ \begin{array}{l} \Delta P_{S_{sup}} \quad v \quad V_{WG} \\ V_{HW} \quad p \quad P_{S_{sup}} \\ J_{HW} \quad p_n \quad K_{P_{sup}} \end{array} \right] \end{array} \right.$$

**Determine mean current**

$$C0(\omega, \rho, D, \Delta t, V_{HG}, \psi_{HG}, N_S, P_S) := \left[ \begin{array}{l} \text{for } j \in 0.. \text{last}(\Delta t) \\ \left[ \begin{array}{l} A_{sup_{j,0}} \leftarrow (N_{S_j})^3 \\ A_{sup_{j,1}} \leftarrow (N_{S_j})^2 \cdot V_{HG_j} \\ A_{sup_{j,2}} \leftarrow (N_{S_j})^2 \cdot \text{dir}(\psi_{HG_j}) \\ A_{sup_{j,3}} \leftarrow A_{sup_{j,2}} \cdot \cos(\omega \cdot \Delta t_j) \\ A_{sup_{j,4}} \leftarrow A_{sup_{j,2}} \cdot \sin(\omega \cdot \Delta t_j) \end{array} \right. \\ X_{sup} \leftarrow \text{geninv}(A_{sup}) \cdot P_S \\ P_{S_{sup}} \leftarrow A_{sup} \cdot X_{sup} \\ \Delta P_{S_{sup}} \leftarrow P_S - P_{S_{sup}} \\ \text{for } k \in 0.. 2 \\ \quad \quad \quad X_{sup_{2+k}} \\ v_k \leftarrow \frac{X_{sup_{2+k}}}{X_{sup_1}} \\ V_{WG.mean} \leftarrow v_0 \\ V_{WG.mean} \end{array} \right.$$

**END**  
**Routines of a quasi-steady**  
**ship 'model' powering trial**